- 1. What is the fundamental property of Linear Time-Invariant (LTI) systems?
- a) They exhibit exponential growth
- b) They display time-varying behavior
- c) Their response is proportional to the input and independent of time
- d) They have a non-linear relationship between input and output

Answer: c) Their response is proportional to the input and independent of time Explanation: LTI systems satisfy the properties of linearity and time-invariance, meaning their response is directly proportional to the input and remains constant over time.

- 2. Which representation is used to describe the output of an LTI system in terms of its impulse response?
- a) Step response
- b) Frequency response
- c) Convolution integral
- d) Impulse response

Answer: c) Convolution integral

Explanation: The output of an LTI system can be obtained by convolving the input signal with the impulse response of the system.

- 3. What is the significance of the impulse response in describing LTI systems?
- a) It represents the response of the system to a unit impulse input
- b) It represents the frequency content of the system
- c) It determines the stability of the system
- d) It represents the time-varying behavior of the system

Answer: a) It represents the response of the system to a unit impulse input Explanation: The impulse response of an LTI system describes how the system responds to a unit impulse input, which in turn characterizes its behavior for any input signal through convolution.

- 4. Which of the following equations represents the relationship between input, output, and impulse response of an LTI system?
- a) Fourier transform
- b) Laplace transform
- c) Difference equation
- d) Convolution integral

Answer: d) Convolution integral

Explanation: The convolution integral expresses the output of an LTI system as the convolution of the input signal with the impulse response of the system.

- 5. Which form of representation is used to describe LTI systems by recursive equations involving current and past inputs and outputs?
- a) Direct form-I
- b) Direct form-II
- c) Transpose
- d) Cascade

Answer: b) Direct form-II

Explanation: Direct form-II representation of LTI systems involves recursive equations relating current and past inputs and outputs, allowing for efficient implementation.

- 6. What property ensures that the impulse response of an LTI system remains bounded for bounded inputs?
- a) Linearity
- b) Time-invariance
- c) Causality
- d) Stability

Answer: d) Stability

Explanation: Stability ensures that the impulse response of an LTI system remains bounded for bounded inputs, indicating that the system's response does not grow uncontrollably over time.

- 7. Which block diagram representation involves the series connection of multiple LTI systems?
- a) Direct form-I
- b) Direct form-II
- c) Cascade
- d) Parallel

Answer: c) Cascade

Explanation: Cascade representation involves connecting multiple LTI systems in series, where the output of one system serves as the input to the next.

- 8. In which block diagram representation are multiple LTI systems connected in parallel, each processing the same input?
- a) Direct form-I
- b) Direct form-II

- c) Cascade
- d) Parallel

Answer: d) Parallel

Explanation: In the parallel representation, multiple LTI systems are connected in parallel, each processing the same input independently.

- 9. Which property ensures that the output of an LTI system depends only on past and present inputs, not future inputs?
- a) Linearity
- b) Time-invariance
- c) Causality
- d) Stability

Answer: c) Causality

Explanation: Causality ensures that the output of an LTI system depends only on past and present inputs, not on future inputs, which is a fundamental property for many practical systems.

- 10. What type of system is characterized by having an impulse response that can be represented as a finite sequence of values?
- a) Continuous-time LTI system
- b) Discrete-time LTI system
- c) Time-varying system
- d) Non-linear system

Answer: b) Discrete-time LTI system

Explanation: Discrete-time LTI systems have impulse responses that can be represented as finite sequences of values, making them suitable for digital signal processing applications.

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